TEL 502E – Detection and Estimation Theory

Spring 2014

Instructors :	İlker Bayram ibayram@itu.edu.tr	
Class Meets :	Tuesday, 9.30 – 12.30, EEB 5307	
Textbook :	Fundamentals of Statistical Signal Processing (Vols. I,II), S. M. Kay, Prentice Hall.	
Supplementary :	An Introduction to Signal Detection and Estimation, H. V. Poor, Springer.	
Webpage :	There's a 'ninova' page, please log in and check.	
Grading :	Homeworks (10%), Midterm exam (40%), Final Exam (50%).	
Attendance :	You need to attend at least 70% of the lectures to sit for the final exam.	
Tentative Course Outline		

- (1) Review of probability theory
- (2) Simple Hypothesis Testing, the Neyman Pearson Lemma
- (3) Bayesian Tests, Multiple Hypothesis Testing
- (4) The detection problem under different scenarios
- (5) The estimation problem, minimum variance unbiased estimators
- (6) The Cramér-Rao bound, sufficient statistics, Rao-Blackwell Theorem
- (7) Linear Estimators, maximum likelihood estimation
- (8) Bayesian estimation, minimum mean square estimators, maximum a posteriori estimators
- (9) The innovations process, Wiener filtering, recursive least squares, the Kalman filter

TEL502E – Homework 1

Due 25.02.2014

1. (a) Suppose that X is a non-negative random variable with a pdf $f_X(t)$ (that is, $f_X(t) = 0$ for t < 0). Show that, for any n > 0 and s > 0,

$$P({X \ge s}) \le \frac{\mathbb{E}(X^n)}{s^n}.$$

(b) Using part (a), show that for an arbitrary random variable Y with $\mathbb{E}(Y) = \mu$,

$$P(\{\mu - \epsilon \le Y \le \mu + \epsilon\}) \ge 1 - \frac{\operatorname{var}(Y)}{\epsilon^2}.$$

(c) Suppose that X_1, X_2, \ldots is a sequence of iid random variables with $\mathbb{E}(X_i) = \mu$, $\operatorname{var}(X_i) = \sigma^2$. Also let,

$$Z_n = \frac{1}{n} \sum_{i=1}^n X_i.$$

Compute $\mathbb{E}(Z_n)$ and $\operatorname{var}(Z_n)$.

(d) Show that

$$\lim_{n \to \infty} P(\{\mu - \epsilon < Z_n < \mu + \epsilon\}) = 1,$$

for any $\epsilon > 0$.

Solution. (a) Keeping in mind that s > 0, we have,

$$P({X \ge s}) = \int_{s}^{\infty} f_{X}(t) dt$$
$$\leq \int_{0}^{s} \frac{t^{n}}{s} f_{X}(t) dt + \int_{s}^{\infty} f_{X}(t) dt$$
$$\leq \int_{0}^{s} \frac{t^{n}}{s} f_{X}(t) dt + \int_{s}^{\infty} \frac{t^{n}}{s^{n}} f_{X}(t) dt$$
$$= \frac{\mathbb{E}(X^{n})}{s^{n}}.$$

This inequality is known as Markov's inequality.

(b) Using Y suppose we define a new random variable as $Z = |Y - \mu|$. Then, using Markov's inequality with n = 2, we have,

$$P(\{Z \ge \epsilon\}) \le \frac{\mathbb{E}(Z^2)}{\epsilon^2} = \frac{\operatorname{var}(Y)}{\epsilon^2}.$$

Observe now that

$$P(\{Z \ge \epsilon\}) + P(\{Z < \epsilon\}) = 1$$

since the two events partition the sample space. This implies,

$$P(\{Z < \epsilon\}) \ge 1 - \frac{\operatorname{var}(Y)}{\epsilon^2}$$

But now observe that

$$\{Z < \epsilon\} = \{|Y - \mu| < \epsilon\} = \{-\epsilon < Y - \mu < \epsilon\} = \{\mu - \epsilon \le Y \le \mu + \epsilon\}$$

Thus the claim follows. This inequality (or an equivalent version) is known as Chebyshev's inequality. (c) First,

$$\mathbb{Z}_n = \frac{1}{n} \sum_{i=1}^n \mathbb{E}(X_i) = \mu.$$

Now, note when the random variables are independent, we can add their variances. Thus,

$$\operatorname{var}(Z_n) = \sum_{i=1}^n \operatorname{var}(X_i/n) = \sum_{i=1}^n \frac{\sigma^2}{n^2} = \frac{\sigma^2}{n}.$$

(d) Since $\mathbb{E}(Z_n) = \mu$, we can use the result of part (b). That gives,

$$P(\{\mu - \epsilon < Z_n < \mu + \epsilon\}) \ge 1 - \frac{\sigma^2}{\epsilon^2 n}.$$

Letting $n \to \infty$, the right hand side converges to 1 and the claim follows.

- 2. (a) Show that if $\operatorname{var}(Y) = 0$, then $P(\{Y = \mathbb{E}(Y)\}) = 1$.
 - (b) Show that if $\mathbb{E}(Y^2) = 0$, then $P(\{Y = 0\}) = 1$.

Solution. (a) Let A be the event of interest defined as,

$$A = \{Y = \mathbb{E}(Y)\}.$$

Instead of P(A), we will compute the $P(A^c)$. Now observe that,

$$A^{c} = \{ |Y - \mathbb{E}(Y)| > 0 \} = \bigcup_{n=1}^{\infty} \underbrace{\{ |Y - \mathbb{E}(Y)| > 1/n \}}_{B_{n}}.$$

But by part (b) of Question-1, we have that $P(B_n) = 0$. Therefore,

$$P(A^c) \le \sum_{n=1}^{\infty} P(B_n) = 0$$

Since $P(A^c) \ge 0$ by definition, it follows that $P(A^c) = 0$. Thus, $P(A) = 1 - P(A^c) = 1$.

- (b) Since $\operatorname{var}(Y) = \mathbb{E}(Y^2) (\mathbb{E}(Y))^2 \ge 0$, the condition $\mathbb{E}(Y^2) = 0$ implies that $\mathbb{E}(Y) = 0$. The desired equality follows therefore follows from part (a).
- 3. Suppose X is a discrete random variable, taking values on the set of integers \mathbb{Z} . Suppose we are testing whether X is distributed according to the probability mass function (PMF) $P_0(t)$ (this is the null hypothesis) or it's distributed according to the PMF $P_1(t)$ (this is the alternative hypothesis). We somehow form the acceptance region $C \subset \mathbb{Z}$ such that if a realization of X, say x falls in C, we accept the null hypothesis, and reject it otherwise. Also, let $p_I(C)$ and $p_{II}(C)$ denote the probabilities of type-I and type-II errors of this test. Below, the parts (a) and (b) are independent of each other.
 - (a) Suppose we discover that for some $r \in (\mathbb{Z} \setminus C)$ and $a_1, a_2, \ldots a_n \in C$,

 - (i) $P_0(r) = \sum_{i=1}^n P_0(a_i)$, and (ii) $(P_0(r)/P_1(r)) > (P_0(a_i)/P_1(a_i))$ for i = 1, 2, ..., n.

Based on this observation, we decide to update the acceptance region and use $D = C \cup \{r\} \setminus \{a_1, \ldots, a_n\}$ as the acceptance region (i.e., we remove a_i 's and include r in the new acceptance region). Let $p_I(D)$ and $p_{II}(D)$ denote the type-I and type-II error probabilities for this updated test. Show that $p_I(D) \leq p_I(C)$, and $p_{II}(D) < p_{II}(C)$.

(b) Suppose we find that for any $r \in (\mathbb{Z} \cap C^c)$, and $a \in C$, the inequality

$$\frac{P_0(r)}{P_1(r)} < \frac{P_0(a)}{P_1(a)} \tag{1}$$

is satisfied. Consider now another test than the one described above with an acceptance region given as D, whose type-I and type-II error probabilities are given as $p_I(D)$ and $p_{II}(D)$ respectively. Show that if $p_I(D) \leq p_I(C)$, then $p_I(D) > p_{II}(D)$.

Solution. Notice that, in this setting, for an acceptance region denoted as C, the type-I and type-II error probabilities are given by

$$p_I(C) = \sum_{x \in \mathbb{Z} \cap C^c} P_0(x), \quad p_{II}(C) = \sum_{x \in C} P_1(x).$$

(a) First, observe that, by condition (i), we have,

$$p_I(D) - p_I(C) = \sum_{z \in \mathbb{Z} \cap D^c} P_0(z) - \sum_{z \in \mathbb{Z} \cap C^c} P_0(z) = \sum_{i=1}^n P_0(a_i) - P_0(r) = 0.$$

Rewriting (ii) as,

$$\frac{P_1(a_i)}{P_1(r)} > \frac{P_0(a_i)}{P_0(r)}, \text{ for } i = 1, 2, \dots, n,$$

and summing over i, we obtain,

$$\frac{\sum_{i=1}^{n} P_1(a_i)}{P_1(r)} > \frac{\sum_{i=1}^{n} P_0(a_i)}{P_0(r)} = 1,$$

where we made use of (i) again. Now observe that,

$$p_{II}(D) - p_{II}(C) = \sum_{z \in D} P_1(z) - \sum_{z \in C} P_1(z) = P_1(r) - \sum_{i=1}^n P_1(a_i) < 0.$$

(b) Suppose $p_I(D) \leq p_I(c)$. This implies,

$$p_I(D) - p_I(C) = \sum_{x \in \mathbb{Z} \cap D^c} P_0(x) - \sum_{x \in \mathbb{Z} \cap C^c} P_0(x) = \sum_{x \in D^c \cap C} P_0(x) - \sum_{x \in C^c \cap D} P_0(x) \le 0,$$

or

$$\frac{\sum_{x \in C^c \cap D} P_0(x)}{\sum_{x \in D^c \cap C} P_0(x)} \ge 1.$$
(2)

Now observe similarly that

$$p_{II}(D) - p_{II}(C) = \sum_{x \in D} P_1(x) - \sum_{x \in C} P_1(x) = \sum_{x \in D \cap C^c} P_1(x) - \sum_{x \in C \cap D^c} P_1(x).$$

Thus, if we can show that

$$\frac{\sum_{x \in D \cap C^c} P_1(x)}{\sum_{x \in C \cap D^c} P_1(x)} > 1,$$
(3)

we are done.

For this, we first rewrite (1) in a different form. Note that if $x \in C^c$ and $c \in C$, then

$$P_1(c) P_0(x) < P_0(c) P_1(x)$$

Fixing $c \in C$, we obtain,

$$P_1(c) \left(\sum_{x \in D \cap C^c} P_0(x)\right) < P_0(c) \left(\sum_{x \in D \cap C^c} P_1(x)\right).$$

Now taking the terms inside the parentheses as fixed, we can write,

$$\left(\sum_{c\in D^c\cap C} P_1(c)\right) \left(\sum_{x\in D\cap C^c} P_0(x)\right) < \left(\sum_{c\in D^c\cap C} P_0(c)\right) \left(\sum_{x\in D\cap C^c} P_1(x)\right).$$

Rewriting and using (2), we obtain (3):

$$\frac{\sum_{x \in D \cap C^c} P_1(x)}{\sum_{x \in D^c \cap C} P_1(x)} > \frac{\sum_{x \in D \cap C^c} P_0(x)}{\sum_{x \in D^c \cap C} P_0(x)} \ge 1.$$

Notice that throughout, I assumed that $P_i(x)$ is non-zero as long as $x \in \mathbb{Z}$. I leave it to you to consider how to modify the argument if $P_i(x) = 0$ from some x.

TEL502E - Homework 2

Due 11.03.2014

1. Consider a hypothesis testing problem as follows. We are given the realisation of a random vector x of length k. There are two hypothesis concerning x, namely H_0 and H_1 , which suggest that x_i 's are of the form

$$H_0: x_i = n_i,$$

$$H_1: x_i = s_i + n_i$$

where $n_1, \ldots n_k$ is the realisation of a random vector with iid zero-mean Gaussian components with variance σ^2 and s_1, \ldots, s_k is a known constant vector. We have seen in class that the Neyman-Pearson test for this scenario employs the test statistic $T(x) = \sum_{i=1}^{k} s_i x_i$ and is of the form

 $\begin{cases} \text{If } T(x) < \gamma, & \text{then decide } H_0 \\ \text{If } T(x) \ge \gamma, & \text{then decide } H_1. \end{cases}$

Recall that the $Q(\cdot)$ function is defined in terms of the pdf of a standard Gaussian random variable $f(\cdot)$ as

$$Q(t) = \int_t^\infty f(s) \, ds = \int_t^\infty \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2}s^2\right) \, ds$$

- (a) Determine γ so that the probability of a Type-I error is α . Express this threshold in terms the $Q(\cdot)$ function.
- (b) For the threshold computed in part (a), find the probability of a Type-II error.
- **Solution.** (a) Recall that a Type-I error occurs when H_0 is true but we decide H_1 . This is equivalent to saying that the event $\{T' < \gamma\}$ where X is assumed to be distributed as an iid Gaussian random vector where each component has variance σ^2 . Now we need to determine how $T' = \sum_i s_i X_i$ is distributed. Note that since T is a linear combination of zero-mean Gaussian random variables, it is also a zero-mean Gaussian random variable. Also, since $s_i X_i$'s are independent, the variances add (why?) and the variance of T' is found to be $\sigma_T^2 = \sigma^2 \sum_i s_i^2 = \sigma^2 \varepsilon^2$, where ε^2 denotes the energy of the deterministic signal s. Observe now that $\sigma_T^{-1}T'$ is a standard Gaussian random variable. Thus, probability of a type-I error can be computed as,

$$P(\text{Type-I}) = P\{T' > \gamma\} \text{ under } H_0$$

= $P\{\sigma_T^{-1}T' > \sigma_T^{-1}\gamma\}$ under H_0
= $Q(\sigma_T^{-1}\gamma).$

If this probability is desired to be less than or equal to α , the γ value that minimizes the probability of a type-II error is, $\gamma = \sigma_T Q^{-1}(\alpha)$.

(b) For the threshold found in part (a), a type-II error occurs if the event $\{T < \gamma\}$ occurs while X is distributed as a random vector with iid entries where X_i is Gaussian with mean s_i and variance σ^2 (this is what H_1 claims). Under this hypothesis, we need to find how $T' = \sum_i s_i X_i$ is distributed. Arguing as in (a), T' is a Gaussian r.v. But this time, the mean is $\sum_i s_i^2 = \varepsilon^2$ (why?) and the variance is $\sigma^2 \sum_i s_i^2 = \sigma^2 \varepsilon^2 = \sigma_T^2$ (as in part (a)). Observe in this case that $\sigma_T^{-1}(T - \varepsilon^2)$ is a standard Gaussian random variable. Thus,

$$P(\text{Type-II}) = P\{T' < \gamma\} \text{ under } H_1$$

= $P\{\sigma_T^{-1}(T' - \varepsilon^2) < \sigma_T^{-1}(\gamma - \varepsilon^2)\}$ under H_1
= $1 - Q(\sigma_T^{-1}(\gamma - \varepsilon^2))$
= $1 - Q(Q^{-1}(\alpha) - \frac{\varepsilon}{\sigma}).$

2. Let us slightly complicate the problem in Question-1 by introducing another constant signal, namely $z = (z_1, \ldots z_k)$, into the scenario. Suppose that the two hypothesis are now of the form,

$$H_0: x_i = z_i + n_i,$$

$$H_1: x_i = s_i + n_i,$$

1

where the rest of the variables are as described in Question-1.

(a) Find a test statistic T'(x) such that the Neyman-Pearson test is of the form

$$\begin{cases} \text{If } T'(x) < \gamma, & \text{then decide } H_0\\ \text{If } T'(x) \ge \gamma, & \text{then decide } H_1. \end{cases}$$

- (b) For the test in part (a), determine the constant γ , in terms of the $Q(\cdot)$ function so that the probability of a Type-I error is equal to α .
- (c) Determine the probability of a Type-II error for the threshold computed in part(b).

Solution. Given x, suppose we define the data vector y = x - z. Also, let r = s - z. Under this change of variables, notice that H_0 and H_1 can be expressed as,

$$\begin{split} H_0 : y_i &= n_i, \\ H_1 : y_i &= r_i + n_i. \end{split}$$

Thus, the problem is reduced to the problem in Question-1. All we need to do is to translate the results while paying attention to the change of variables.

(a) Note that under this change of variables, one can use

$$\sum_{i} r_{i} y_{i} = \sum_{i} (s_{i} - z_{i}) (x_{i} - z_{i}) = \sum_{i} (s_{i} - z_{i}) x_{i} + \text{const.}$$

as a statistic. Dropping the constant term, we find a test statistic given as $T' = \sum_i (s_i - z_i) X_i$.

- (b) Let $\varepsilon^2 = \sum_i (s_i z_i)^2$. Then, the best threshold is (see Question-1 part(a)), $\gamma = \sigma \varepsilon Q^{-1}(\alpha)$.
- (c) In this case, for $\varepsilon = \sum_i (s_i z_i)^2$, the probability of a type-II error is (see Question-1, part(b)),

$$P(\text{Type-II}) = 1 - Q\left(Q^{-1}(\alpha) - \frac{\varepsilon}{\sigma}\right).$$

TEL502E – Homework 3

Due 22.04.2014

1. Suppose X_1 , X_2 are independent identically distributed random variables with a probability density function (pdf) given as,

$$f(t) = \frac{1}{2} e^{-|t|}.$$

We make two observations y_1 , y_2 , related to realizations of X_i 's. Suppose there are two hypotheses concerning the observations

 $H_0: y_i = x_i, \text{ for } i = 1, 2,$ $H_1: y_i = 2 x_i, \text{ for } i = 1, 2,$

where x_i 's are realizations of X_i 's.

- (a) Find the pdf of Y_1 under H_1 .
- (b) Find the Neyman-Pearson test for the given hypotheses. That is, find a test statistic $g(y_1, y_2)$ such that

$$\begin{cases} \text{if } g(y_1, y_2) > \gamma, & \text{then we decide } H_0, \\ \text{if } g(y_1, y_2) \le \gamma, & \text{then we decide } H_1. \end{cases}$$

(c) For the test in part (b), find the threshold γ so that the probability of a Type-I error is α . (Recall that we make a Type-I error if we decide H_1 while H_0 is true.)

Solution. (a) To write the pdf let us first find the cdf :

$$F_{Y_1}(t) = P(Y_1 \le t) = P(2X_1 \le t) = F_X(t/2).$$

Differentiating, we obtain,

$$f_{Y_1}(t) = \frac{1}{2} f_X(t/2) = \frac{1}{4} e^{-|t|/2}.$$

(b) The LRT statistic for this problem is,

$$T = \frac{f_0(y_1, y_2)}{f_1(y_1, y_2)} = \frac{1}{2} \exp\left(-\left(|y_1| + |y_2|\right)/2\right)$$

Note that the test is of the form,

$$\begin{cases} \text{If } T \ge \beta, & \text{decide } H_0 \\ \text{If } T < \beta, & \text{decide } H_1. \end{cases}$$

Taking logarithms, we find an equivalent test as,

$$\begin{cases} \text{If } -(|y_1|+|y_2|) \geq \gamma, & \text{decide } H_0\\ \text{If } -(|y_1|+|y_2|) < \gamma, & \text{decide } H_1 \end{cases}$$

Therefore $g(y_1, y_2) = -(|y_1| + |y_2|)$ works.

(c) In order to evaluate the probability of error, we need to find the pdf pf the test statistic. Let us first find the pdf of $U_1 = |Y_1|$. Note that the cdf of U_1 is,

$$F_{U_1}(t) = P(U_1 \le t) = \begin{cases} 2 \int_0^t f_{Y_1}(s) \, ds, & \text{if } t \ge 0, \\ 0, & \text{if } t < 0. \end{cases}$$

Differentiating with respect to t, we find the pdf of U_1 as,

$$f_{U_1}(t) = \begin{cases} 2 f_{Y_1}(t) = e^{-|t|}, & \text{if } t \ge 0, \\ 0, & \text{if } t < 0. \end{cases}$$

Now let $S = U_1 + U_2$. Since U_1 and U_2 are independent (note that they are also identically distributed). The pdf of S can be found by convolving the pdfs of U_1 and U_2 .

$$f_S(t) = \begin{cases} \int_0^t e^{-(t-s)} e^{-s} \, ds = t \, e^{-t}, & \text{if } t > 0, \\ 0, & \text{if } t < 0. \end{cases}$$

Now observe that

$$P(g > \gamma) = P(S < -\gamma)$$

= $\int_0^{-\gamma} t e^{-t} dt$
= $(-t e^{-t})|_0^{-\gamma} + \int_0^{-\gamma} e^{-t} dt$
= $\gamma e^{\gamma} + (1 - e^{\gamma}).$

Therefore if

$$h(\gamma) = 1 + (\gamma - 1)e^{\gamma} = \alpha,$$

set $\gamma = h^{-1}(\alpha)$ (note that $h(\gamma)$ is invertible for $\gamma < 0$).

2. Suppose we observe a signal x_i for i = 1, 2, ..., k. There are two hypothesis of the form,

$$H_0: x_i = z_i + n_i,$$

$$H_1: x_i = s_i + n_i,$$

where z_i and s_i are deterministic (and known signals) and n_i 's are realizations of iid Gaussian random variables with unit variance.

(a) Find a test statistic T(x) such that the Neyman-Pearson test is of the form

$$\begin{cases} \text{If } T(x) < \gamma, & \text{then decide } H_0 \\ \text{If } T(x) \ge \gamma, & \text{then decide } H_1. \end{cases}$$

(b) Recall that the Q function is defined as,

$$Q(t) = \int_t^\infty \frac{1}{\sqrt{2\pi}} e^{-t^2/2} dt.$$

For the test in part (a), determine the constant γ , in terms of the $Q(\cdot)$ function so that the probability of a Type-I error is equal to α .

- (c) Determine the probability of a Type-II error for the threshold computed in part(b).
 - (Recall that we make a Type-II error if we decide H_0 while H_1 is true.)
- **Solution.** (a) Let f_i , denote pdf of the data under the hypothesis H_i . Then the LRT statistic is given by,

$$\frac{f_0}{f_1} = \exp\left(-\sum_{i=1}^n \left[(x_i - z_i)^2 - (x_i - s_i)^2\right]\right) \\ = \exp\left(-\sum_{i=1}^n \left[2x_i \left(s_i - z_i\right) + (s_i - z_i)^2\right]\right)$$

Taking logarithms and discarding constanat terms, we find a test equivalent to the LRT as,

$$\underbrace{\sum_{i=1}^{n} x_i(s_i - z_i)}_{T(x)} \begin{cases} < \gamma & \Rightarrow \text{ decide } H_0, \\ \ge \gamma & \Rightarrow \text{ decide } H_1. \end{cases}$$

(b) Note that under H_0 , T(X) is distributed as a Gaussian with mean $\mu = \sum_i z_i(s_i - z_i)$ and variance $\sigma^2 = \sum_i (z_i - s_i)^2$. Therefore, the probability of a type-I error is,

$$P(T > \gamma) = P\left(\frac{T-\mu}{\sigma} > \frac{\gamma-\mu}{\sigma}\right) = Q\left(\frac{\gamma-\mu}{\sigma}\right).$$

If this is to be equal to α , the threshold γ should be,

$$\gamma = Q^{-1}(\alpha)\sigma + \mu.$$

(c) Under H_1 , T(X) is distributed as a Gaussian with mean $\hat{\mu} = \sum_i s_i(s_i - z_i)$ and variance $\sigma^2 = \sum_i (z_i - s_i)^2$. Therefore, the probability of a type-II error is,

$$P(T < \gamma) = P\left(\frac{T - \hat{\mu}}{\sigma} > \frac{\gamma - \hat{\mu}}{\sigma}\right) = 1 - Q\left(\frac{\gamma - \hat{\mu}}{\sigma}\right) = 1 - Q\left(Q^{-1}(\alpha) - \sqrt{\sum_{i=1}^{n} (z_i - s_i)^2}\right).$$

3. Let X_1, X_2 be independent Gaussian random variables with the same mean θ but with different variances σ_1^2, σ_2^2 . That is, the probability density functions of X_1 and X_2 are,

$$f_1(t) = \frac{1}{\sqrt{2\pi\sigma_1^2}} \exp\left(-\frac{(t-\theta)^2}{2\sigma_1^2}\right),$$

$$f_2(t) = \frac{1}{\sqrt{2\pi\sigma_2^2}} \exp\left(-\frac{(t-\theta)^2}{2\sigma_2^2}\right).$$

- (a) Find an expression for the Cramér-Rao lower bound for θ (in terms of σ_1^2 and σ_2^2).
- (b) Find the uniformly minimum variance unbiased (UMVU) estimator for θ .

Solution. Note that the joint pdf of $X = (X_1, X_2)$ is the product of the two pdfs. We compute

$$\mathbb{E}\left(\left[\frac{\partial}{\partial\theta}\ln f(t_1, t_2; \theta)\right]^2\right) = \mathbb{E}\left(\left[\frac{1}{\sigma_1^2}(\theta - X_1) + \frac{1}{\sigma_2^2}(\theta - X_2)\right]^2\right)$$
$$= \mathbb{E}\left(\frac{1}{\sigma_1^4}(\theta - X_1)^2 + \frac{1}{\sigma_2^4}(\theta - X_2)^2\right)$$
$$= \sigma_1^{-2} + \sigma_2^{-2}.$$

Therefore the CRLB is $(\sigma_1^{-2} + \sigma_2^{-2})^{-1}$.

Note that we can write,

$$\frac{\partial}{\partial \theta} \ln f(X_1, X_2; \theta) = \underbrace{\left(\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}\right)}_{\sigma^{-2}} \theta - \frac{X_1}{\sigma_1^2} - \frac{X_2}{\sigma_1^2}$$
$$= \underbrace{\left(\frac{1}{\sigma_1^2} + \frac{1}{\sigma_2^2}\right)}_{\theta(X_1, X_2)} \left[\theta - \underbrace{\left(\frac{\sigma^2}{\sigma_1^2} X_1 + \frac{\sigma^2}{\sigma_2^2} X_2\right)}_{\hat{\theta}(X_1, X_2)}\right].$$

Thus, $\hat{\theta}(X_1, X_2)$ must be the UMVUE.

4. Suppose X_1 , X_2 , X_3 are independent random variables uniformly distributed on $[0, \theta]$. Recall that a random variable uniformly distributed on $[0, \theta]$ has pdf

$$f(t) = \begin{cases} \theta^{-1}, & \text{if } t \in [0, \theta], \\ 0, & \text{if } t \notin [0, \theta]. \end{cases}$$

We are interested in the value of θ .

(a) A student suggests $\hat{\theta} = X_1 + X_2 + X_3$ as an estimator. Find out whether this estimator is biased or not. If it is biased, derive an unbiased estimator $\tilde{\theta}$ which is a function of $\hat{\theta}$ only (i.e., the other random variables do not appear in the new expression).

- (b) An unbiased estimator for θ is $\bar{\theta} = X_1 + X_2$. Compare the variances of $\bar{\theta}$ and $\tilde{\theta}$ that you found in part (a). Which would you prefer to use as an estimator of θ and why?
- **Solution.** (a) Note that $\mathbb{E}(X_i) = \theta/2$. Therefore, $\mathbb{E}(X_1 + X_2 + X_3) = 3\theta/2 \neq \theta$. Therefore $\hat{\theta}$ biased, but $\tilde{\theta} = 2\theta/3$ is unbiased.
- (b) Note that $\operatorname{var} X_i = \theta^2/12$. Since X_i 's are independent, we can add their variance to find $\operatorname{var}(\bar{\theta}) = \operatorname{var}(X_1) + \operatorname{var}(X_2) = \theta^2/6$. Similarly, we find $\operatorname{var}(\tilde{\theta}) = (4/9) \operatorname{var} X_1 + (4/9) \operatorname{var} X_2 + (4/9) \operatorname{var} X_3 = \theta^2/9$. I'd prefer $\tilde{\theta}$ over $\bar{\theta}$ because it has uniformly lower variance.

TEL 502E – Detection and Estimation Theory

Midterm Examination

25.03.2014

(25 pts) 1. Suppose X_1 , X_2 are independent identically distributed random variables with a probability density function (pdf) given as,

 $f(t) = \frac{1}{2} e^{-|t|}$

We make two observations y_1 , y_2 , related to realizations of X_i 's. Suppose there are two hypotheses concerning the observations

 $H_0: y_i = x_i, \text{ for } i = 1, 2,$ $H_1: y_i = 2 x_i, \text{ for } i = 1, 2,$

where x_i 's are realizations of X_i 's.

- (a) Find the pdf of Y_1 under H_1 .
- (b) Find the Neyman-Pearson test for the given hypotheses. That is, find a test statistic $g(y_1, y_2)$ such that

 $\begin{cases} \text{if } g(y_1, y_2) > \gamma, & \text{then we decide } H_0, \\ \text{if } g(y_1, y_2) \le \gamma, & \text{then we decide } H_1. \end{cases}$

- (c) For the test in part (b), find the threshold γ so that the probability of a Type-I error is α . (Recall that we make a Type-I error if we decide H_1 while H_0 is true.)
- (25 pts) 2. Suppose we observe a signal x_i for i = 1, 2, ..., k. There are two hypothesis of the form,

 $H_0: x_i = z_i + n_i,$ $H_1: x_i = s_i + n_i,$

where z_i and s_i are deterministic (and known signals) and n_i 's are realizations of iid Gaussian random variables with unit variance.

(a) Find a test statistic T(x) such that the Neyman-Pearson test is of the form

 $\begin{cases} \text{If } T(x) < \gamma, & \text{then decide } H_0 \\ \text{If } T(x) \ge \gamma, & \text{then decide } H_1. \end{cases}$

(b) Recall that the Q function is defined as,

$$Q(t) = \int_{t}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-t^{2}/2} dt$$

For the test in part (a), determine the constant γ , in terms of the $Q(\cdot)$ function so that the probability of a Type-I error is equal to α .

(c) Determine the probability of a Type-II error for the threshold computed in part(b). (Recall that we make a Type-II error if we decide H_0 while H_1 is true.)

(25 pts) 3. Let X_1, X_2 be independent Gaussian random variables with the same mean θ but with different variances σ_1^2, σ_2^2 . That is, the probability density functions of X_1 and X_2 are,

$$\begin{split} f_1(t) &= \frac{1}{\sqrt{2\pi\,\sigma_1^2}}\,\exp\left(-\frac{(t-\theta)^2}{2\sigma_1^2}\right),\\ f_2(t) &= \frac{1}{\sqrt{2\pi\,\sigma_2^2}}\,\exp\left(-\frac{(t-\theta)^2}{2\sigma_2^2}\right). \end{split}$$

(a) Find an expression for the Cramér-Rao lower bound for θ (in terms of σ_1^2 and σ_2^2).

- (b) Find the uniformly minimum variance unbiased (UMVU) estimator for θ .
- (25 pts) 4. Suppose X_1 , X_2 , X_3 are independent random variables uniformly distributed on $[0, \theta]$. Recall that a random variable uniformly distributed on $[0, \theta]$ has pdf

 $f(t) = \begin{cases} \theta^{-1}, & \text{if } t \in [0, 1], \\ 0, & \text{if } t \notin [0, 1]. \end{cases}$

We are interested in the value of $\theta.$

- (a) A student suggests $\hat{\theta} = X_1 + X_2 + X_3$ as an estimator. Find out whether this estimator is biased or not. If it is biased, derive an unbiased estimator $\tilde{\theta}$ which is a function of $\hat{\theta}$ only (i.e., the other random variables do not appear in the new expression).
- (b) An unbiased estimator for θ is $\bar{\theta} = X_1 + X_2$. Compare the variances of $\bar{\theta}$ and $\tilde{\theta}$ that you found in part (a). Which would you prefer to use as an estimator of θ and why?

TEL 502E – Detection and Estimation Theory

Final Examination

23.05.2014

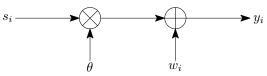
Student Name : _____

Student Num. : _____

5 Questions, 120 Minutes

Please Show Your Work for Full Credit!

(20 pts) 1. Consider a system as shown below, where a stochastic process s_i is modulated with a constant θ and then contaminated with additive noise w_i giving observations y_i , for i = 1, 2, ..., n.



Suppose that the samples s_i are independent Gaussian random variables with mean 1 and variance σ^2 . Suppose also that w_i 's are independent zero-mean Gaussian random variables with variance β^2 .

 θ can take one of two values $\{0, 1\}$. Let H_0 denote the hypothesis that $\theta = 0$, and H_1 denote the hypothesis that $\theta = 1$.

- (a) Find the probability density function (pdf) of the observations y_i under H_1 .
- (b) Find the Neyman-Pearson test for testing H_0 against H_1 .
- (20 pts) 2. Consider a discrete random variable X whose probability mass function (pmf) depends on a parameter θ , where $\theta \in \{0, 1, 2\}$. Suppose that X takes values in $\{0, 1, 2, 3\}$ and its pmf for different values of θ , denoted by $P(x|\theta)$, is as given below.

x	$P(x \theta = 0)$	$P(x \theta = 1)$	$P(x \theta = 2)$
0	1/8	1/4	0
1	1/4	1/2	1/3
2	3/8	1/8	1/3
3	1/4	1/8	1/3

Please provide a brief explanation of your answers for full credit.

- (a) Suppose we are given a realization of X as x = 1. Find the maximum likelihood estimate (MLE) for θ .
- (b) Suppose we are given two independent realizations of X as $x_1 = 1$, $x_2 = 2$. Find the MLE for θ .

- (20 pts) 3. Consider a disk with an unknown radius r. We are interested in the area of the disk. For this, we measure the radius n times but each measurement contains some error. Specifically, suppose that the measurements are of the form $X_i = r + Z_i$ for i = 1, 2, ..., n, where Z_i 's are independent zero-mean Gaussian random variables with known variance σ^2 .
 - (a) Find a sufficient statistic for r.
 - (b) A professor suggests that we use

$$\hat{A} = \pi \left(\frac{1}{n} \sum_{i=1}^{n} X_i^2 \right)$$

as an estimator of the area. Determine if \hat{A} is biased or not.

- (c) Find the uniformly minimum variance unbiased estimator for the area of the disk.
- (20 pts) 4. Let X_1, X_2 be independent Gaussian random variables with mean θ and variance 1. Also, let θ be a random variable uniformly distributed on [0, 1] that is, the pdf of θ is given by,

$$f_{\theta}(t) = \begin{cases} 1, & \text{if } t \in [0, 1], \\ 0, & \text{if } t \notin [0, 1]. \end{cases}$$

- (a) Find the joint pdf of θ , X_1 , X_2 . That is, find $f_{\theta,X_1,X_2}(t,x_1,x_2)$.
- (b) Find the maximum a posteriori (MAP) estimate of θ .
- (c) Evaluate the estimator you found in part (b) if the data is as given below.
 - (i) $x_1 = 3/4, x_2 = 1.$
 - (ii) $x_1 = 1/2, x_2 = 2.$

(20 pts) 5. Suppose a discrete-time system produces data of the form

$$X(n) = A_0 + A_1 n + Z_n,$$

where A_0 , A_1 and Z_n are independent random variables. Assume that A_0 and A_1 are identically distributed with zero-mean and variance equal to σ^2 . Also, suppose Z_n denotes a sequence of identically distributed zero-mean random variables with variance equal to β^2 . Finally let X denote the samples at n = 0, 1, 2, which are made available to us, that is, $X = \begin{bmatrix} X(0) & X(1) & X(2) \end{bmatrix}^T$.

- (a) Find the covariance matrix of X, namely C.
- (b) Find an expression for the linear minimum mean square estimate (LMMSE) of A_0 , given the vector X. (Note : Do not try to invert C, just use C^{-1} .)
- (c) Find an expression for the LMMSE of A_1 , given the vector X.